

LIMOBILE M1 Pro

High-precision Mobile Laser Scanning System



The LiMobile M1 Pro is a survey-grade high-precision mobile laser scanning(MLS) system developed by GVI. The device integrates long-range high-precision LiDAR, high-precision GNSS/INS integrated navigation system, and high-resolution panoramic camera. It also provides abundant expansion interfaces and can be installed on different vehicle types. Together with LiDAR360 MLS software from GVI, it enables a one-stop data processing to the delivery of industry results.

Advantages

I High Precision

Integrated LiDAR with millimeter measurement accuracy, system accuracy up to centimeter level.

I High Efficiency

Laser range up to 420 m, effective measurment rate up to 1 000 000 meas./sec.

I Real-time Monitoring

Support the display of collected data and monitor the operating status of the equipment in the web interface in real-time.

I Multi-sensor

Integration of high-precision LiDAR, GNSS/INS integrated navigation system, and high-resolution panoramic camera, enabling the acquisition of high-definition point cloud data and imagery data.

I Abundant Expansions

Hot-swappable hard disk, DMI, USB 3.0, LAN.

I Multi-industry Applications

Widely used in areas such as road maintenance, road expansion, road asset survey, smart transportation, high-definition map, digital twins, and more.





Specifications

System Speci	Tications							
Size		530 mm×319 mm×655 mm			Battery Capacity		5700 mAh×6	
Data Storage		512 GB SSD + 2 TB Hot-swappable hard disk			Weight		17.2 kg	
Operating Time		≥ 4 h			Port HDMI、USB、LAN			
System Control and Data Display		Wireless mode			The Tablet is connected to the WIFI of the device for operation control and data synchronization display			
					The tablet is connected to the device via a data cable for data transmission and control			
Applicable Environment		Outdoor			Processor 4 Cores and 8 Threads			
LiDAR Specifi	cations							
Sensor Model		RIEGL VUX-1HA			Precision		3 mm	
Scan Speed		10 - 250 revolutions per - 250 scans/sec		r second, equivalent to 10	Horizontal FOV		360°	
Laser Pulse Repetition Rate				300 kHz	500 kHz) kHz		1000 kHz
Maximum range		Target reflectivity >	10%	150 m	120 m		100 m	85 m
		Target reflectivity > 80%		420 m	330 m	330 m		235 m
Positioning a	nd Orienta	tion System	Specifi	cations				
GNSS System		GPS: L1C/A, L1C, L2C, L GLONASS: L1C/A, L2C, I BEIDOU: B1, B2, B3 GALILEO: E1, E5a, E5b			IMU Update Rate		100 Hz	
Accelerometer	Bias In-run Stability		0.02	5 mg (1ơ)		Bias In-	-run Stability	0.25° /hr (1ơ)
	Bias Repeatability		1.7 n	ng (1ơ)		Bias Re	Sias Repeatability 7° /hr (1ơ)	
	VRW		0.03	m/s/ √hr	Gyro	ARW		0.04° / √hr
	Operating	erating Range		g		Operat	ing Range	< 200°/s
Ladybug5+ Pa	anoramic (Camera Spec	ificatio	ns				
Pixels		30 MP (5 MP x 6 sensors)		s)	Sensor Type	CMOS		
Frame Rate		30 FPS (JPEG Compressed)		Sensor Size		2/3 "		
Resolution		8192×4096			Power Consumption		13 W maximum	
Data Output								
Absolute Accuracy		$\leq 0.030 \text{ m RMS}^{[1]}$			Point Cloud Data Format Las, Laz, LiData			
Software								
Pre-processing Software		LiGeoreference		Post-processing Software LiDAR360 MLS				
[1]May be affected	hu anuiranna			toro				